

**Tables and diagrams relating to crystallography referenced as 'Dr Arnott'.**

**Contributors**

Arnott, Struther, b.1934

**Publication/Creation**

February 1967

**Persistent URL**

<https://wellcomecollection.org/works/c29kgak2>

**License and attribution**

You have permission to make copies of this work under a Creative Commons, Attribution, Non-commercial license.

Non-commercial use includes private study, academic research, teaching, and other activities that are not primarily intended for, or directed towards, commercial advantage or private monetary compensation. See the Legal Code for further information.

Image source should be attributed as specified in the full catalogue record. If no source is given the image should be attributed to Wellcome Collection.



Wellcome Collection  
183 Euston Road  
London NW1 2BE UK  
T +44 (0)20 7611 8722  
E [library@wellcomecollection.org](mailto:library@wellcomecollection.org)  
<https://wellcomecollection.org>

2595

hence there  
when  
direction in the glide plane.  
roups,

# Symbols of Two-dimensional Symmetry Operators

Point symmetry (1st position)			Line symmetry (2nd and 3rd positions)		
Printed symbol	Graphical symbol	Operator	Printed symbol	Graphical symbol	Operator
2		2-fold (180°) point	<i>m</i>		Mirror-reflection line of symmetry
3		3-fold (120°) point			
4		4-fold (90°) point	<i>g</i>		Glide-reflection line with translation of one half the repeat distance along the line
6		6-fold (60°) point			

NOTE. The symbol 1 denotes the identity operation and hence the absence of any other (point or line) symmetry.

### Symmetry Symbols

In the diagrams of space groups, heights are indicated in the manner described above for equivalent general positions. In the case of glide planes, the glide translation  $\tau$  along an axis always implies a reflection in the plane. The symbols for glide planes do not apply to equivalent positions.

The graphical symbols used in the drawings are given in Tables 4.1.6 and 4.1.7, which also give the nature of the translations corresponding to the various symbols.

TABLE 4.1.6 Symbols of Symmetry Planes

Symbol	Symmetry plane	Graphical symbol		Nature of glide translation
		Normal to plane of projection	Parallel to plane of projection	
$m$	Reflection plane (mirror)			None (NOTE. If the plane is at $z = \frac{1}{2}$ this is shown by printing $\frac{1}{2}$ beside the symbol.)
$a, b$	Axial glide plane			$a/2$ along $[100]$ or $b/2$ along $[010]$ ; or along $\langle 100 \rangle$ .
$c$			None	$c/2$ along $z$ -axis; or $(a+b+c)/2$ along $[111]$ on rhombohedral axes.
$n$	Diagonal glide plane (net)			$(a+b)/2$ or $(b+c)/2$ or $(c+a)/2$ ; or $(a+b+c)/2$ (tetragonal and cubic).
$d$	"Diamond" glide plane			$(a \pm b)/4$ or $(b \pm c)/4$ or $(c \pm a)/4$ ; or $(a \pm b \pm c)/4$ (tetragonal and cubic). See note below.

NOTE. In the "diamond" glide plane the glide translation is half of the resultant of the two possible axial glide translations. The arrows in the first diagram show the direction of the horizontal component of the translation when the  $z$ -component is positive. In the second diagram the arrow shows the actual direction of the glide translation; there is always another diamond-glide reflection plane parallel to the first with a height difference of  $\frac{1}{4}$  and with the arrow pointing along the other diagonal of the cell face.

Symbols of Symmetry Axes

Symbol	Symmetry axis	Graphical symbol	Nature of right-handed screw translation along the axis	Symbol	Symmetry axis	Graphical symbol (normal to plane of paper)	Nature of right-handed screw translation along the axis
1	Rotation monad	None	None	4	Rotation tetrad		None
$\bar{1}$	Inversion monad		None	$4_1$	Screw tetrads		$c/4$
2	Rotation diad	 (normal to paper)  (parallel to paper)	None	$4_2$			$2c/4$
				$4_3$			$3c/4$
$2_1$	Screw diad	 (normal to paper)  (parallel to paper) Normal to paper	$c/2$ Either $a/2$ or $b/2$	4	Inversion tetrad		None
3	Rotation triad		None	6	Rotation hexad		None
$3_1$	Screw triads		$c/3$	$6_1$	Screw hexads		$c/6$
$3_2$			$2c/3$	$6_2$			$2c/6$
$\bar{3}$	Inversion triad		None	$6_3$			$3c/6$
				$6_4$			$4c/6$
				$6_5$			$5c/6$
				$\bar{6}$	Inversion hexad		None

In any space-group symbol the order in which the various parts of the symbol are written is, in general, the same as in the corresponding point groups (see Table 3.3.2).

The nomenclature described is sufficient to cover all but four of the 230 space groups. A convention is necessary to distinguish between the members of the pairs  $I222$ ,  $I2_12_12_1$  and  $I23$ ,  $I2_13$ . This arises because in all four of these groups both 2-fold rotation and screw axes are present in each of three mutually perpendicular directions denoted, the arrangement in space of these axes being distinguished by the conventional symbol to distinguish between the two cases. In the first case, in which all three 2-fold rotation axes intersect in a point (the three screw axes intersecting in another point), as in the groups  $I222$  and  $I2_12_12_1$ , the symbol  $I222$  is used where this intersection of all three axes of the same kind

ΣΣΡ5

## [II-5] THE CRYSTAL AS A GEOMETRICAL FIGURE

TABLE I. THE 32 CRYSTAL CLASSES

(The eleven classes of distinct Laue symmetry are separated by vertical lines)

System	Axes and angles			Crystal classes (point groups)			
Triclinic	$a$ $\alpha$	$b$ $\beta$	$c$ $\gamma$	1 $C_1$	$\bar{1}$ $C_i$		
Monoclinic	$a$ $90^\circ$	$b$ $\beta$	$c$ $90^\circ$	2 $C_2$	$m$ or $\bar{2}$ $C_s$	$2/m$ $C_{2h}$	
Orthorhombic	$a$ $90^\circ$	$b$ $90^\circ$	$c$ $90^\circ$				$222$ $D_2$   $mm2$ $C_{2v}$   $mmm$ $D_{2h}$
Tetragonal	$a$ $90^\circ$	$a$ $90^\circ$	$c$ $90^\circ$	4 $C_4$	$\bar{4}$ $S_4$	$4/m$ $C_{4h}$	$422$ $D_4$   $4mm$ $C_{4v}$   $\bar{4}2m$ $D_{2d}$   $4/mmm$ $D_{4h}$
Trigonal (rhombohedral)	$aaa$ $\alpha\alpha\alpha$ or	$a$ $90^\circ$	$a$ $90^\circ$	3 $C_3$	$\bar{3}$ $C_{3i}$		$32$ $D_3$   $3m$ $C_{3v}$   $\bar{3}m$ $D_{3d}$
Hexagonal	$a$ $90^\circ$	$a$ $90^\circ$	$c$ $120^\circ$	6 $C_6$	$\bar{6}$ $C_{3h}$	$6/m$ $C_{6h}$	$622$ $D_6$   $6mm$ $C_{6v}$   $\bar{6}m2$ $D_{3h}$   $6/mmm$ $D_{6h}$
Cubic	$a$ $90^\circ$	$a$ $90^\circ$	$a$ $90^\circ$	23 $T$	$m\bar{3}$ $T_h$		$432$ $O$   $\bar{4}3m$ $T_d$   $m\bar{3}m$ $O_h$

This gives rise to the seven well-known crystallographic systems, and the arrangement generally adopted is shown in Table I. Reference axes are also indicated, and these range from the triclinic system, where the three axes are inclined at any angle, to the hexagonal system, where the three axes are mutually perpendicular.

While the 3-fold axis is characteristic of the rhombohedral system, it should be noted that this system cannot be based exclusively on the rhombohedral lattice (see Chapter III). When the space groups (Table III) are developed from these points, it is found that the simple cubic lattice has

product sign indicating that the operations denoted by the symbols are applied in succession. Also

$$m^2 = 1, \quad \bar{1}^2 = 1, \quad 2^2 = 1.$$

It may be noted that all the operations of such a group leave one point unmoved. In the geometrical figures all axes of symmetry and any planes of symmetry must pass through such a fixed point, which is called the center of the group, a group of this kind is called a *point group*. If there were two parallel axes of symmetry, or two parallel

planes of symmetry at a fixed distance apart, the operation of one on the other, or of one axis on the other, would produce a third and so on to infinity, the figure thus becoming indefinitely extended.

#### LIMITATION OF

solid bodies. Geometrical figures constructed to

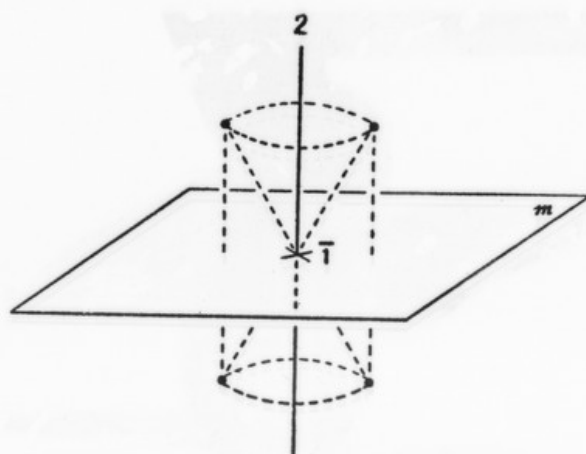
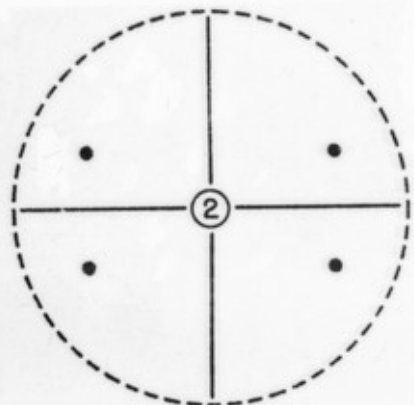


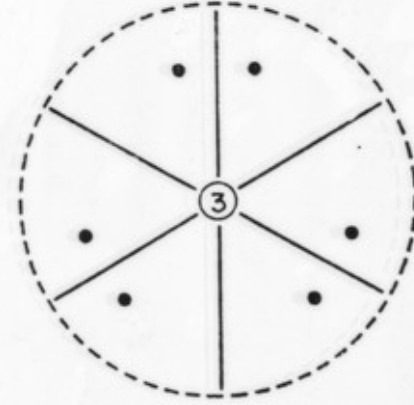
Fig. 2. The group  $2m\bar{1}$ .

2295

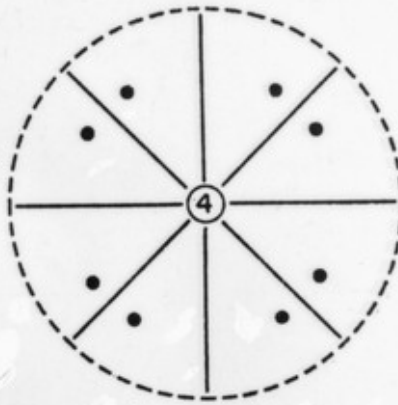
axis brings it into self-coincidence and gives rise to the groups of Fig. 8 and one,  $3/m = \bar{6}$  ( $C_{3h}$ ), already mentioned above (5). The introduction of a reflection plane *parallel* to the  $n$ -fold axis gives rise to a set of such planes equal in number to the multiplicity of the axis. These groups are illustrated



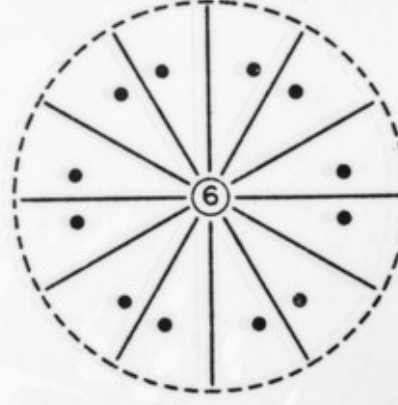
$mm2(C_{2v})$



$3m(C_{3v})$



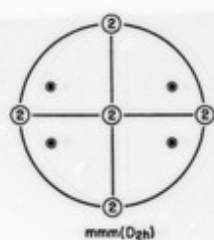
$4mm(C_{4v})$



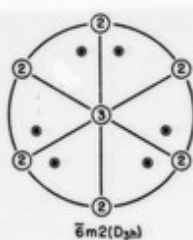
$6mm(C_{6v})$

Point groups,  $C_{2v}-C_{6v}$ .

9, and are analogous to those of Fig. 6. A reflection plane can also be introduced perpendicular to the  $n$ -fold axis of the groups  $D_2-D_6$  (Fig. 6), giving rise to the four further groups 10. In the case of  $D_2$  and  $D_3$  (Fig. 6), reflection planes can be introduced bisecting



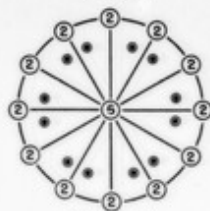
$mmm(D_{2h})$



$\bar{6}m2(D_{3h})$

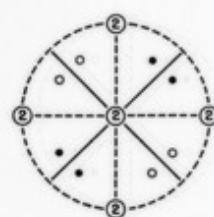


$4/mmm(D_{4h})$

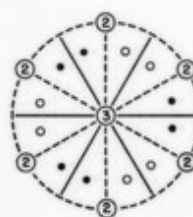


$6/mmm(D_{6h})$

Point groups,  $D_{2k}-D_{6k}$ .

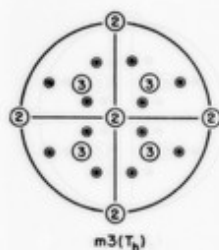


$\bar{4}2m(D_{2d})$

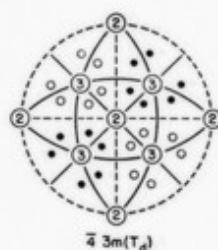


$\bar{3}m(D_{3d})$

Point groups,  $D_{2d}$  and  $D_{3d}$ .



$m\bar{3}(T_d)$



$\bar{4}3m(T_d)$



$m\bar{3}m(O_h)$

Point groups,  $T_d$ ,  $T_d$ , and  $O_h$ .



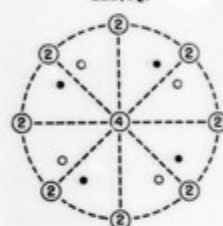
# ORGANIC CRYSTALS AND MOLECULES



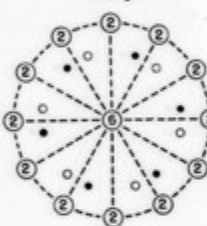
222( $D_2$ )



32( $D_3$ )

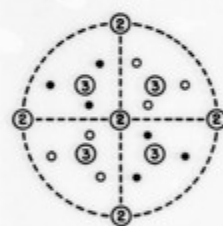


422( $D_4$ )

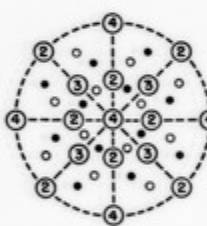


622( $D_6$ )

Point groups,  $D_2$ - $D_6$ .



23( $T$ )

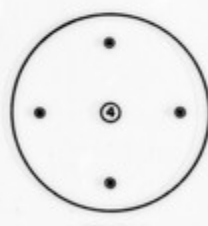


432( $O$ )

Point groups,  $T$  and  $O$ .



2/m( $C_{2h}$ )



4/m( $C_{4h}$ )

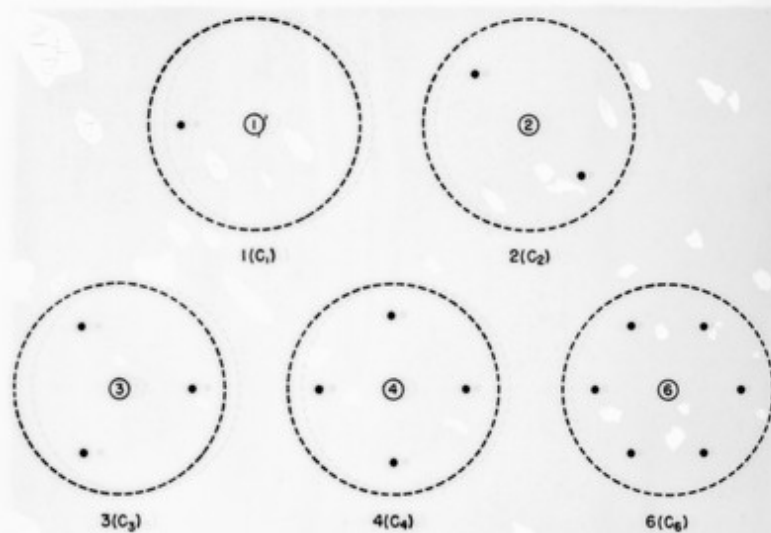


6/m( $C_{6h}$ )

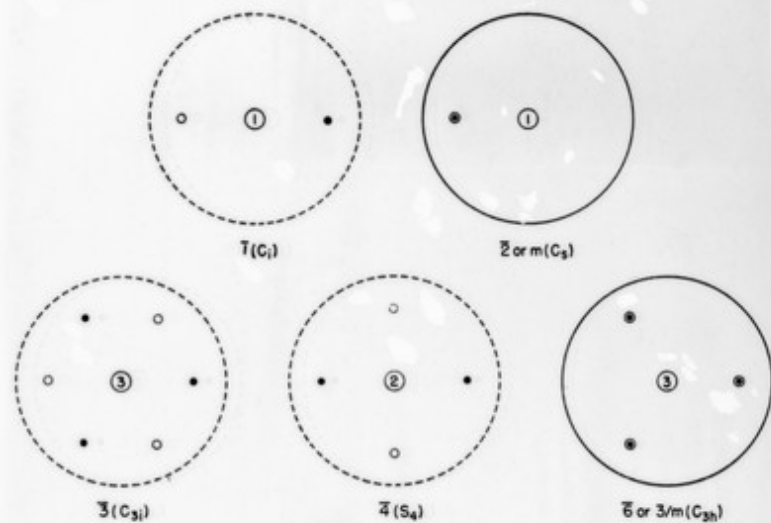
Point groups,  $C_{2h}$ - $C_{6h}$ .

[II-5]

URE



Point groups, 1-6.



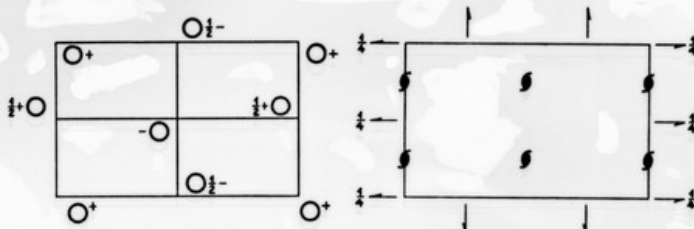
Point groups, 7-9.

Orthorhombic 222

$P 2_1 2_1 2_1$

No. 19

$P 2_1 2_1 2_1$   
 $D_2^4$



Origin halfway between three pairs of non-intersecting screw axes

Number of positions,  
Wyckoff notation,  
and point symmetry

4  $a$  1

Co-ordinates of equivalent positions

$x, y, z$ ;  $\frac{1}{2} - x, \frac{1}{2} + y, \frac{1}{2} + z$ ;  $\frac{1}{2} + x, \frac{1}{2} - y, \frac{1}{2} + z$ ;  $\bar{x}, \frac{1}{2} + y, \frac{1}{2} - z$ .

Conditions limiting  
possible reflections

$hkl$ :  
 $0kl$ :  
 $h0l$ :  
 $hk0$ :  
 $h00$ :  $h = 2n$   
 $0k0$ :  $k = 2n$   
 $00l$ :  $l = 2n$

No conditions

Symmetry of special projections

(001)  $pgg$ ;  $a' = a, b' = b$

(100)  $pgg$ ;  $b' = b, c' = c$

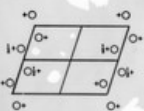
(010)  $pgg$ ;  $c' = c, a' = a$

**B2**  
**C<sub>2</sub><sup>3</sup>**

No. 5

**B112**

2 Monoclinic



1st SETTING  
Number of positions,  
Wyckoff notation,  
and point symmetry

4 c 1 x,y,z; x,y,z.  
2 b 2 0,1/2,x.  
2 a 2 0,0,x.

(001) p2; a' = a/2, b' = b

Origin on 2; unique axis c  
Co-ordinates of equivalent positions  
(0,0,0); 1/2,1/2,1

Symmetry of special projections  
(100) pm1; b' = b, c' = c/2

Conditions limiting  
possible reflections

General:  
hkl: h = l - 2n  
hk0: (h = 2n)  
00l: (l = 2n)

Special: as above only

(010) c1c; c' = c, a' = a

Monoclinic 2

**C121**

No. 5

**C2**  
**C<sub>2</sub><sup>3</sup>**



Number of positions,  
Wyckoff notation,  
and point symmetry

4 c 1 x,y,z; x,y,z.  
2 b 2 0,1/2,x.  
2 a 2 0,0,x.

(001) cml; a' = a, b' = b

Origin on 2; unique axis b  
Co-ordinates of equivalent positions  
(0,0,0); 1/2,1/2,1

Symmetry of special projections  
(100) p1c; b' = b/2, c' = c

2nd SETTING  
Conditions limiting  
possible reflections

General:  
hkl: h = k - 2n  
hk0: (h = 2n)  
00l: (l = 2n)

Special: as above only

(010) p2; c' = c, a' = a/2

first results, obtained by M. L. Frankenheim,<sup>3</sup> were not entirely satisfactory, but rigid geometrical proofs were obtained soon afterwards by Auguste Bravais,<sup>4</sup> who demonstrated that only 14 distinct types of space lattices are possible.

2

regularly distributed in space, which are the subject of Bravais's investigation, we may proceed in three steps. A rectilinear system of equidistant points, extending indefinitely in both directions, is called a *row*

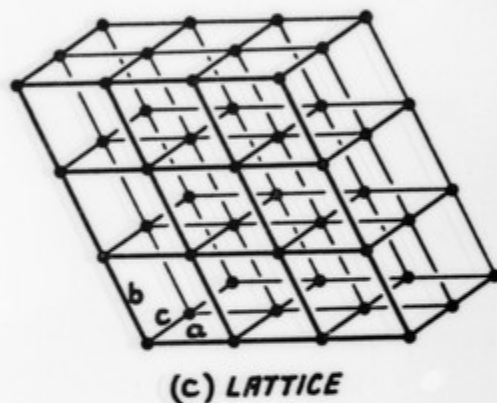
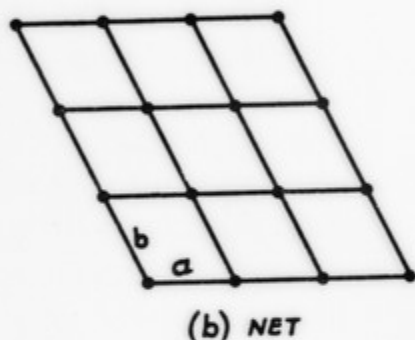
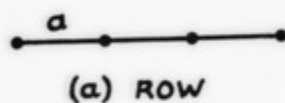


Fig. 15. Lattices and nets.

(Fig. 15a), and is fully described by one parameter,  $a$ , the fundamental interval separating two neighbouring points. A regular series of such parallel rows, lying in one plane, can be described by two fundamental intervals,  $a$  and  $b$ , and an arbitrary angle  $\gamma$ . This is called a *net* (Fig. 15b). The system of points regularly distributed in three dimensions consists of an indefinitely extended regular series of parallel nets, and can be described by three fundamental intervals,  $a$ ,  $b$ , and  $c$ , together with three arbitrary angles,  $\alpha$ ,  $\beta$ , and  $\gamma$ . Such a system is called a *lattice* (Fig. 15c). The smallest parallelepiped which is identically

<sup>3</sup> M. L. Frankenheim, *Die Lehre von der Cohäsion*, Breslau, 1835; also *Nova Acta Acad. Caes. Leopoldino-Carolinae Nat. Cur.*, 1842, 19(2), 471-660.

<sup>4</sup> Auguste Bravais, "Mémoire sur les systèmes formés par des points distribués régulièrement sur un plan ou dans l'espace, *J. école polytechn.*, 1846, 33, 375-445. Translated by A. Stokes, *Cambridge Science American*, 1906, 1, 1-10.